

## ECE351 HW#5: Solutions

2.44. If  $y(t) = x(t) * h(t)$  is the output of an LTI system with input  $x(t)$  and impulse response  $h(t)$ , then show that

$$\frac{d}{dt}y(t) = x(t) * \left(\frac{d}{dt}h(t)\right)$$

and

$$\frac{d}{dt}y(t) = \left(\frac{d}{dt}x(t)\right) * h(t)$$

$$\begin{aligned}\frac{d}{dt}y(t) &= \frac{d}{dt}x(t) * h(t) \\ &= \frac{d}{dt} \int_{-\infty}^{\infty} x(\tau)h(t - \tau)d\tau\end{aligned}$$

Assuming that the functions are sufficiently smooth, the derivative can be pulled through the integral

$$\frac{d}{dt}y(t) = \int_{-\infty}^{\infty} x(\tau) \frac{d}{dt}h(t - \tau)d\tau$$

Since  $x(\tau)$  is independent of  $t$

$$\frac{d}{dt}y(t) = x(t) * \left(\frac{d}{dt}h(t)\right)$$

The convolution integral can also be written as

$$\begin{aligned}\frac{d}{dt}y(t) &= \frac{d}{dt} \int_{-\infty}^{\infty} h(\tau)x(t - \tau)d\tau \\ &= \int_{-\infty}^{\infty} h(\tau) \frac{d}{dt}x(t - \tau)d\tau \\ &= \left(\frac{d}{dt}x(t)\right) * h(t)\end{aligned}$$

2.50. Evaluate the step response for the LTI systems represented by the following impulse responses:  
(a)  $h[n] = (-1/2)^n u[n]$

**Solution:**

When the input is  $u[n]$ ,

the output  $s[n] = \sum_{k=-\infty}^{\infty} (-1/2)^k u[k]u[n-k]$ .

for  $n < 0$

$$s[n] = 0$$

for  $n \geq 0$

$$s[n] = \sum_{k=0}^n \left(-\frac{1}{2}\right)^k$$

$$s[n] = \frac{1}{3} \left(2 + \left(-\frac{1}{2}\right)^n\right)$$

$$s[n] = \begin{cases} \frac{1}{3} \left(2 + \left(-\frac{1}{2}\right)^n\right) & n \geq 0 \\ 0 & n < 0 \end{cases}$$

(b)  $h[n] = \delta[n] - \delta[n-2]$

Solution:

When the input is  $u[n]$ ,

$$\text{the output } s[n] = \sum_{k=-\infty}^{\infty} (\delta[k] - \delta[k-2])u[n-k].$$

$$\text{for } n < 0, \quad s[n] = 0;$$

$$\text{for } n = 0 \text{ or } 1, \quad s[n] = 1;$$

$$\text{for } n > 1, \quad s[n] = 0.$$

(e)  $h(t) = e^{-|t|}$

for  $t < 0$

$$s(t) = \int_{-\infty}^t e^{\tau} d\tau = e^t$$

for  $t \geq 0$

$$s(t) = \int_{-\infty}^0 e^{\tau} d\tau + \int_0^t e^{-\tau} d\tau = 2 - e^{-t}$$

$$s(t) = \begin{cases} e^t & t < 0 \\ 2 - e^{-t} & t \geq 0 \end{cases}$$

(g)  $h(t) = (1/4)(u(t) - u(t-4))$

for  $t < 0$

$$s(t) = 0$$

for  $0 \leq t < 4$

$$s(t) = \frac{1}{4} \int_0^t d\tau = \frac{1}{4}t$$

for  $t \geq 4$

$$s(t) = \frac{1}{4} \int_0^4 d\tau = 1$$

$$s(t) = \begin{cases} 0 & t < 0 \\ \frac{1}{4}t & 0 \leq t < 4 \\ 1 & t \geq 4 \end{cases}$$

2.57. Determine the output of the systems described by the following differential equations with input and initial conditions as specified:

(a)  $\frac{d}{dt}y(t) + 10y(t) = 2x(t)$ ,  $y(0^-) = 1$ ,  $x(t) = u(t)$

$$\begin{aligned}
 t \geq 0 & \quad \text{natural: characteristic equation} \\
 r + 10 & = 0 \\
 r & = -10 \\
 y^{(n)}(t) & = ce^{-10t} \\
 & \quad \text{particular} \\
 y^{(p)}(t) & = ku(t) = \frac{1}{5}u(t) \\
 y(t) & = \frac{1}{5} + ce^{-10t} \\
 y(0^-) = 1 & = \frac{1}{5} + c \\
 c & = \frac{4}{5} \\
 y(t) & = \frac{1}{5} [1 + 4e^{-10t}] u(t)
 \end{aligned}$$

2.59. Determine the output of the systems described by the following difference equations with input and initial conditions as specified:

(a)  $y[n] - \frac{1}{2}y[n-1] = 2x[n]$ ,  $y[-1] = 3$ ,  $x[n] = \left(\frac{-1}{2}\right)^n u[n]$

$$\begin{aligned}
 n \geq 0 & \quad \text{natural: characteristic equation} \\
 r - \frac{1}{2} & = 0 \\
 y^{(n)}[n] & = c \left(\frac{1}{2}\right)^n \\
 & \quad \text{particular} \\
 y^{(p)}[n] & = k \left(-\frac{1}{2}\right)^n u[n] \\
 k \left(-\frac{1}{2}\right)^n - \frac{1}{2}k \left(-\frac{1}{2}\right)^{n-1} & = 2 \left(-\frac{1}{2}\right)^n \\
 k & = 1 \\
 y^{(p)}[n] & = \left(-\frac{1}{2}\right)^n u[n] \\
 & \quad \text{Translate initial conditions} \\
 y[n] & = \frac{1}{2}y[n-1] + 2x[n] \\
 y[0] & = \frac{1}{2}3 + 2 = \frac{7}{2} \\
 y[n] & = \left(-\frac{1}{2}\right)^n u[n] + c \left(\frac{1}{2}\right)^n u[n] \\
 \frac{7}{2} & = 1 + c \\
 c & = \frac{5}{2} \\
 y[n] & = \left(-\frac{1}{2}\right)^n u[n] + \frac{5}{2} \left(\frac{1}{2}\right)^n u[n]
 \end{aligned}$$

**3.56.** Determine the appropriate Fourier representation for the following time-domain signals, using the defining equations.

(a)  $x(t) = e^{-t} \cos(2\pi t)u(t)$

Continuous and Nonperiodic, use FT.

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt \\ &= \frac{1}{2} \int_0^{\infty} e^{-t}(e^{j2\pi t} + e^{-j2\pi t})e^{-j\omega t} dt \\ &= \frac{1}{2} \int_0^{\infty} e^{-t(1-j2\pi+j\omega)} dt + \frac{1}{2} \int_0^{\infty} e^{-t(1+j2\pi+j\omega)} dt \\ &= \frac{1}{2} \left[ \frac{1}{1-j(2\pi-\omega)} + \frac{1}{1+j(2\pi+\omega)} \right] \end{aligned}$$

(b)  $x[n] = \begin{cases} \cos(\frac{\pi}{10}n) + j \sin(\frac{\pi}{10}n), & |n| < 10 \\ 0, & \text{otherwise} \end{cases}$

Discrete and Nonperiodic, use DTFT.

$$\begin{aligned} X(e^{j\Omega}) &= \sum_{n=-\infty}^{\infty} x[n]e^{-j\Omega n} \\ \text{and } x[n] &= e^{j\frac{\pi}{10}n}, |n| < 10 \\ \Rightarrow X(e^{j\Omega}) &= \sum_{n=-9}^9 e^{j(\frac{\pi}{10}-\Omega)n} \\ &= e^{-j9(\frac{\pi}{10}-\Omega)} \frac{1 - e^{j19(\frac{\pi}{10}-\Omega)}}{1 - e^{j(\frac{\pi}{10}-\Omega)}} \end{aligned}$$

(c)  $x[n]$  as depicted in Figure P3.56 (a)

Discrete and Periodic, use DTFS.

We know the fundamental period  $N = 7$  and the fundamental frequency  $\Omega_0 = 2\pi / N$ .

So  $X[k] = \frac{1}{N} \sum_{n=0}^{N-1} x[n]e^{-jk\Omega_0 n}$ , where  $x[0]=1, x[3]=1, x[4]=-1$ , and  $x[1]=x[2]=x[4]=x[6]=0$

$$= \frac{1}{7}(1 + e^{-j\frac{6\pi}{7}k} - e^{-j\frac{8\pi}{7}k})$$

(e)  $x(t) = |\sin(2\pi t)|$

Continuous and Periodic, use FS.

$T = \frac{1}{2}, \omega_o = 4\pi$

$$\begin{aligned} X[k] &= 2 \int_0^{0.5} \frac{e^{j2\pi t} - e^{-j2\pi t}}{2j} e^{-j4\pi kt} dt \\ &= -j \int_0^{0.5} e^{j2\pi(1-2k)t} dt - j \int_0^{0.5} e^{-j2\pi(1+2k)t} dt \\ &= \frac{1 - (-1)^{1-2k}}{2\pi(1-2k)} + \frac{1 - (-1)^{(1+2k)}}{2\pi(1+2k)} \end{aligned}$$

% ECE351. Solution to Matlab Experiment 2.86

```
n = 0:3;
% Generate h1[n]
h1 = 0.25*ones(size(n));
% Generate h2[n]
h2 = 0.25*(-1).^n;
% Generate step function as input
u = ones(1, 20);
```

```
% Step response for h1
y1 = conv(u, h1);
% Step response for h2
y2 = conv(u, h2);
```

```
figure;
stem(0:19, y1(1:20));
figure;
stem(0:19, y2(1:20));
```

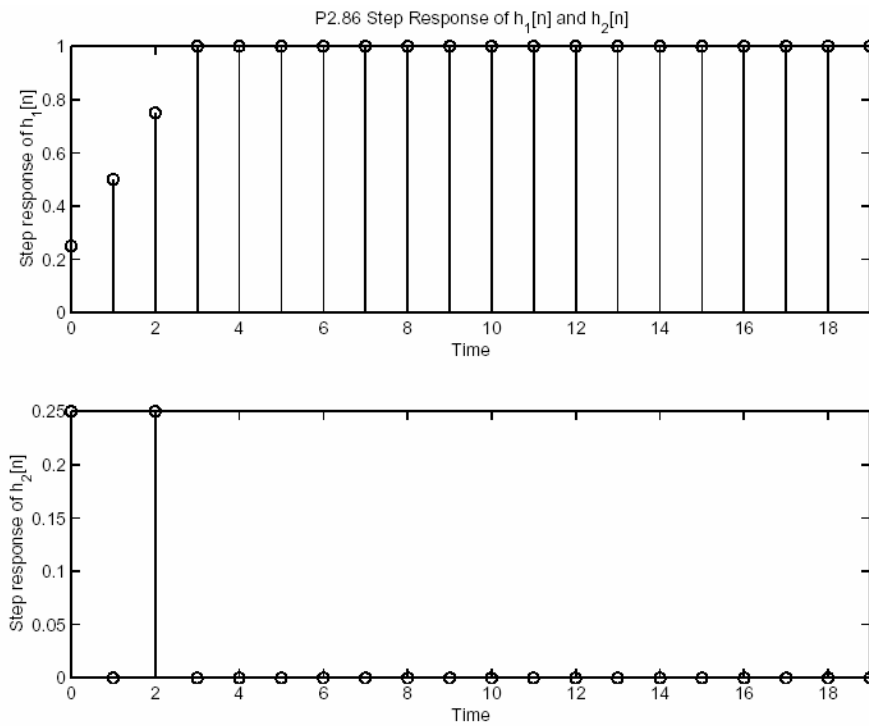


Figure P2.86. Step Response of the two systems

```
% ECE351. Solution to Matlab Experiment Part (3)
```

```
n = -2:4;
```

```
N = 5;
```

```
% Generate x[n]
```

```
x = zeros(size(n));
```

```
x(n== -1) = 0.5;
```

```
x(n== 0) = 1;
```

```
x(n== 1) = -0.5;
```

```
x(n== 4) = 0.5;
```

```
% Generate DTFS coefficients
```

```
for k = -5:5
```

```
    X1(k+6) = sum( x(n>=-2 & n<=2) .* exp(-j*k*(-2:2)*2*pi/N) ) / N;
```

```
    X2(k+6) = sum( x(n>=0 & n<=4) .* exp(-j*k*(0:4)*2*pi/N) ) / N;
```

```
end
```

```
X1
```

```
X2
```

**Output:**

```
>> X1 =
```

```
Columns 1 through 4
```

```
0.2000 + 0.0000i 0.2000 + 0.1902i 0.2000 + 0.1176i 0.2000 - 0.1176i
```

```
Columns 5 through 8
```

```
0.2000 - 0.1902i 0.2000 0.2000 + 0.1902i 0.2000 + 0.1176i
```

```
Columns 9 through 11
```

```
0.2000 - 0.1176i 0.2000 - 0.1902i 0.2000 - 0.0000i
```

```
>> X2 =
```

```
Columns 1 through 4
```

```
0.2000 - 0.0000i 0.2000 + 0.1902i 0.2000 + 0.1176i 0.2000 - 0.1176i
```

```
Columns 5 through 8
```

```
0.2000 - 0.1902i 0.2000 0.2000 + 0.1902i 0.2000 + 0.1176i
```

```
Columns 9 through 11
```

```
0.2000 - 0.1176i 0.2000 - 0.1902i 0.2000 + 0.0000i
```